





# **HEATER PANEL**





















# Deals In Almost every major brand acceptable worldwide.





















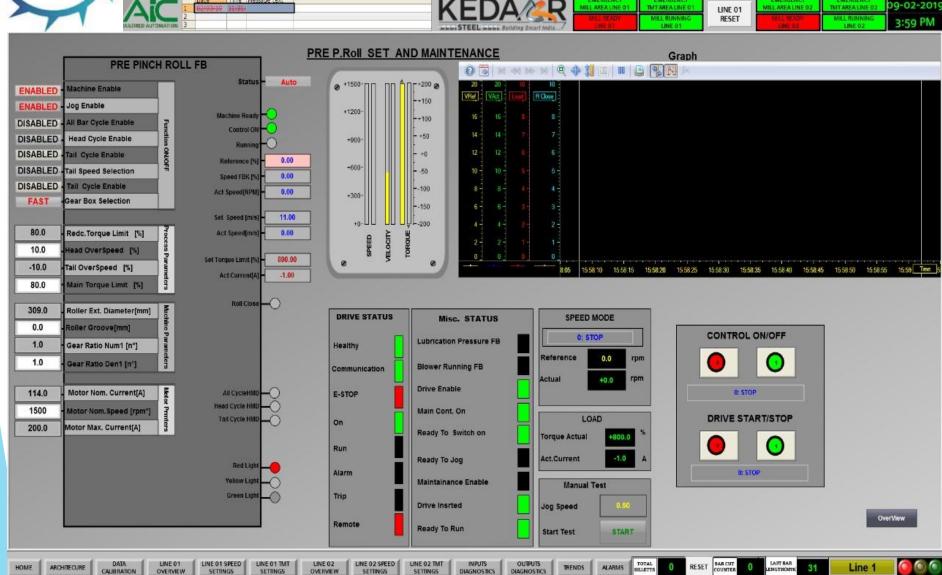




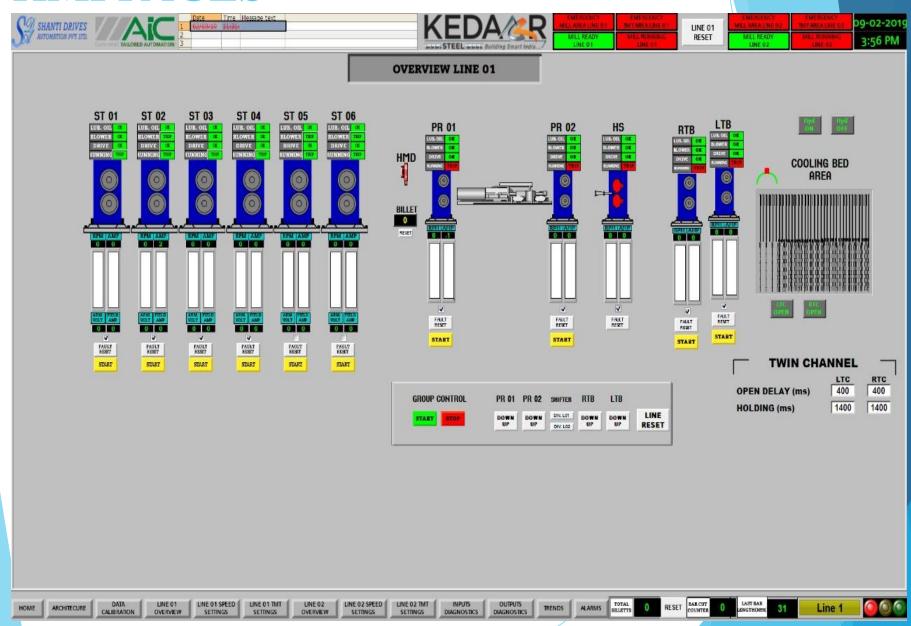


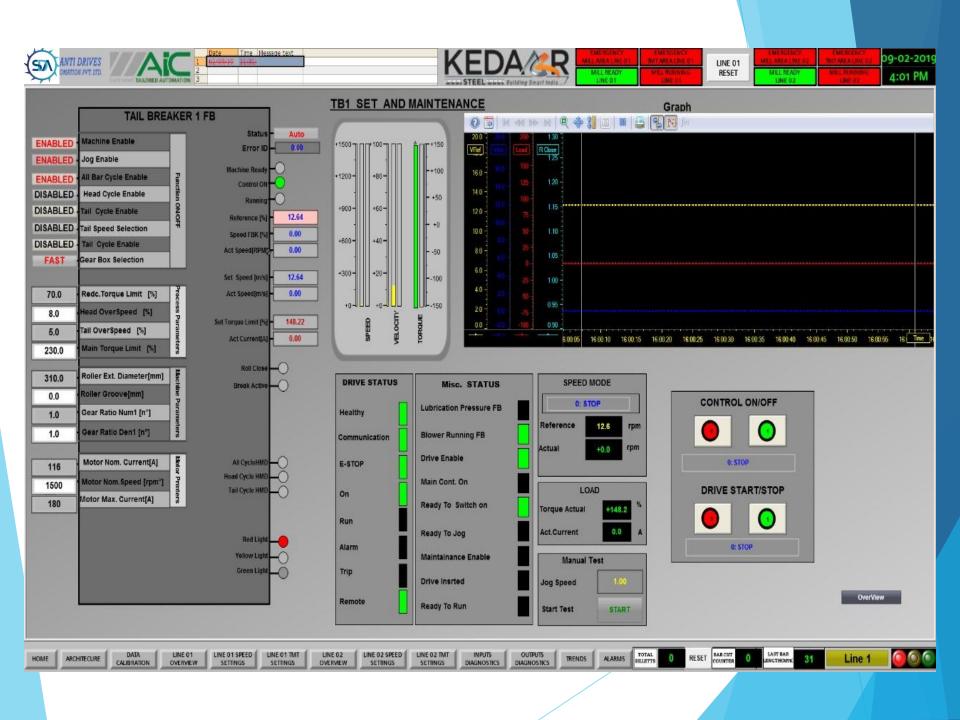


### HMI SCREENS MILL OVERVIEW



## **HMI PAGES**









LINE 01 RESET

09-02-2019 4:01 PM

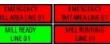
#### Tail Breaker Work Paramentrer









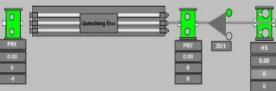


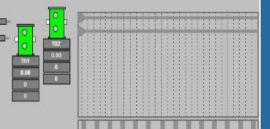
LINE 01 RESET

MILL READY

09-02-2019 3:58 PM







MACHINE	PARAMETERS	U.M.	SETTING	RECIPE	MACHINE	PARAMETERS	U.M.	SETTING	RECIPE
	Head Lead Speed	[%]	+10.0			Measure Cut Length	[m]	51.10	
	Tail Lead Speed	[%]	-10.0		Dividing	Correction Measure Cut Length	[mm]	-1000	
	Reduction Torque Limit(After Head Biting Set Current Limit)	[%]	80.0		C.Shear	First Cut Correction	[mm]	+9000	
	Delay to Remove Limit Torque	[m]	10.00			Minimum Last Bar Length	[m]	5.300	
Pre Pre	Delay to Open After Cycle (Roll Open Delay)	[m]	1.00			TB1 Main Torque Limit	[5]	230.0	
Pinch Roll	Delay to Close Distance(Roll Close Delay )	[m]	1.00			Torque Limit in Reduction	[%]	70.0	
	Close Duration (Head Cycle Enable)	[mm]	1			Head Overspeed	[%]	+8.0	
	Hrnd 2 Delay to Close on Tail (Tail Cycle Enable)	[m]	1.00			Tail Overspeed	[%]	+5.0	
	Work Torque Limit(Main Current Limit)	[%]	80.0			Delay Space Breaking Length Bar	[m]	1.00	
					TB1	Ramp Space Breaking Length Bar	[m]	1.80	
	Head Lead Speed	[%]	+11.0			Speed Breaking Length Bar	[m/s]	5.80	
	Tall Lead Speed	[%]	-10.0			IAST Bar Breaking Speed	[m/s]	6.50	
	Reduction Torque Limit(After Head Biting Set Current Limit)	[%]	100.0			Delay Closing Rolls	[m]	6.00	
1 -0-700	Delay to Remove Limit Torque	[m]	1.00			Delay Opening Rolls	[m]	5.30	
Post Pinch Roll	Delay to Open After Cycle (Roll Open Delay)	[m]	-10.00			TB2 Main Torque Limit	[%]	230.0	
PHICH ROIL	Delay to Close Distance(Roll Close Delay )	[m]	-10.00			Torque Limit In Reduction	[%]	70.0	
	Close Duration (Head Cycle Enable)	[mm]	1			Head Overspeed	[%]	+8.0	
	Hmd 2 Delay to Close on Tail (Tail Cycle Enable)	[m]	+1.00			Tail Overspeed	[%]	+0.5	
	Work Torque Limit(Main Current Limit)	[%]	+100.0			Delay Space Breaking Length Bar	[m]	1.10	
					TB2	Ramp Space Breaking Length Bar	[m]	2.00	
	Time for start to cut positon L1	[ms]	+111			Speed Breaking Length Bar	[m/s]	5.80	
	Time for start to cut position L2	[ms]	+111			IAST Bar Breaking Speed	[m/s]	6.50	
Shifter	Offset Correction time for L1	[m/s]	-25			Delay Closing Rolls	[m]	5.00	
20.000	Offset Correction time for L2	[m/s]	-24			Delay Opening Rolls	[m]	5.00	
	Offset Correction time for L1	[deg]	+0			Last Bar Breaking Holding Time TB1 & TB2	[m]	3.00	

PR1 SP & Maint.

PR2 SP & Maint.

HS SP & Maint.

TB1 SP & Maint.

TB2 SP & Maint.

TB Work

ARCHITECURE HOME

DATA CALIBRATION LINE 01 OVERVIEW SETTINGS

LINE 01 SPEED | LINE 01 TMT SETTINGS

LINE 02 OVERVIEW LINE 02 SPEED | LINE 02 TMT SETTINGS

INPUTS DIAGNOSTICS SETTINGS

OUTPUTS DIAGNOSTICS TRENDS

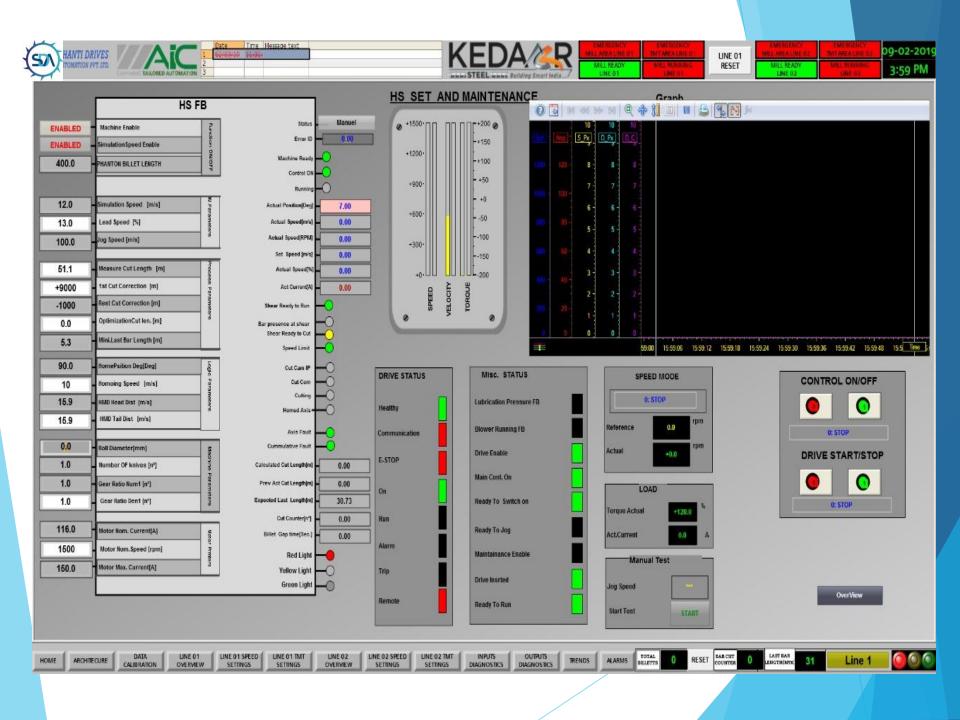
TOTAL BULETTS ALARMS

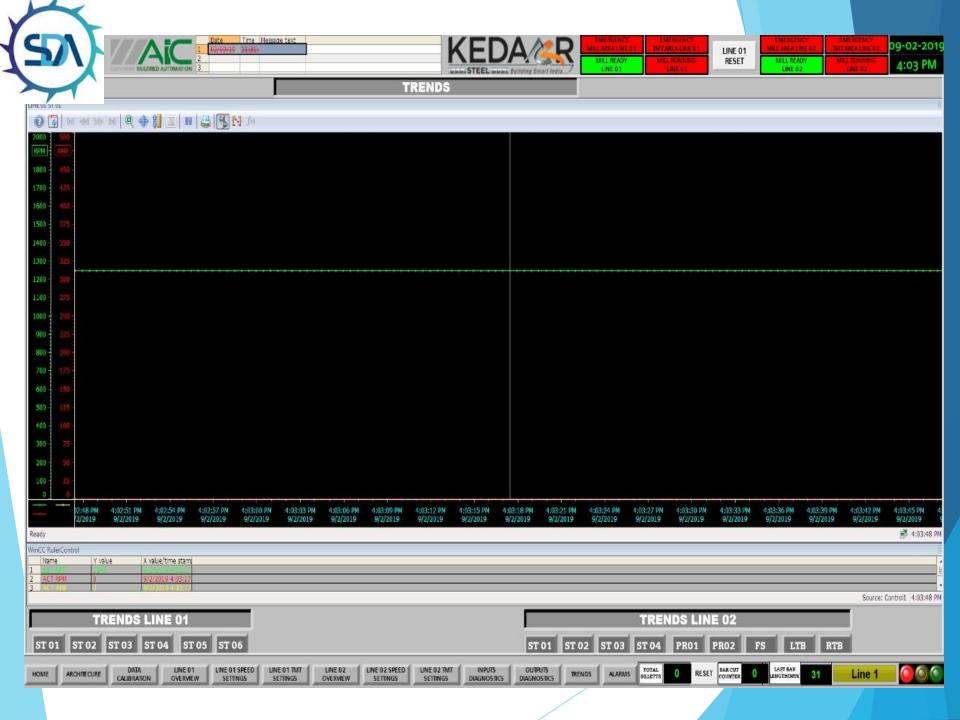
RESET BARCUT

LAST BAR LENGTH(MTK)

Line 1









ST 01 ST 02 ST 03 ST 04 ST 05

ST 06

1800

630

WEAL		Date	Time	Message text	2
	1	02/09/29	11:31:01 AM		
	. 2				



EMERGENCY TMT AREA LINE 0

LINE 01 RESET

EMERGENCY MILL AREA LINE D2

09-02-2019

3:55 PM

### **MILL DATA CALIBRATION**

### STANDS AREA LINE 01

	AX				
RPM	CURRENT	GEAR RATIO	ROLL DIAMETER	GROOVE DIAMETER	WORKING
1800	630	3.110	286	0.00	286
1800	630	2.400	264	0.00	264
1800	630	2.050	277	0.00	277
1800	630	1.680	270	0.00	270
1800	630	1.340	268	0.00	268

1.150

### **TMT AREA LINE 01**

		GEAR	ROLL
RPM	CURRENT	RATIO	DIAMETER
1000	100	1.000	200
1000	100	1.000	200
1000	100	1.000	200
1000	100	1.000	200
1000	100	1.000	200
	1000 1000 1000 1000	1000         100           1000         100           1000         100           1000         100	VALUES RPM         GEAR CURRENT         GEAR RATIO           1000         1.000         1.000           1000         100         1.000           1000         100         1.000           1000         100         1.000

### DISTANCES FROM HMD (mm) LINE 01

PR 1	PR 2	FS	LTB	RTB
0	0	0	0	0

### STANDS AREA LINE 02

283

0.00

283

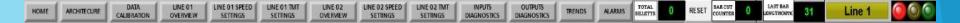
		LUES CURRENT	GEAR	ROLL	GROOVE	WORKING
ST 01	1800	630	2.230	DIAMETER 284	0.00	284
ST 02	1800	630	1.620	284	0.00	284
ST 03	1000	100	1.000	200	0.00	200
ST 04	1000	100	1.000	200	0.00	200

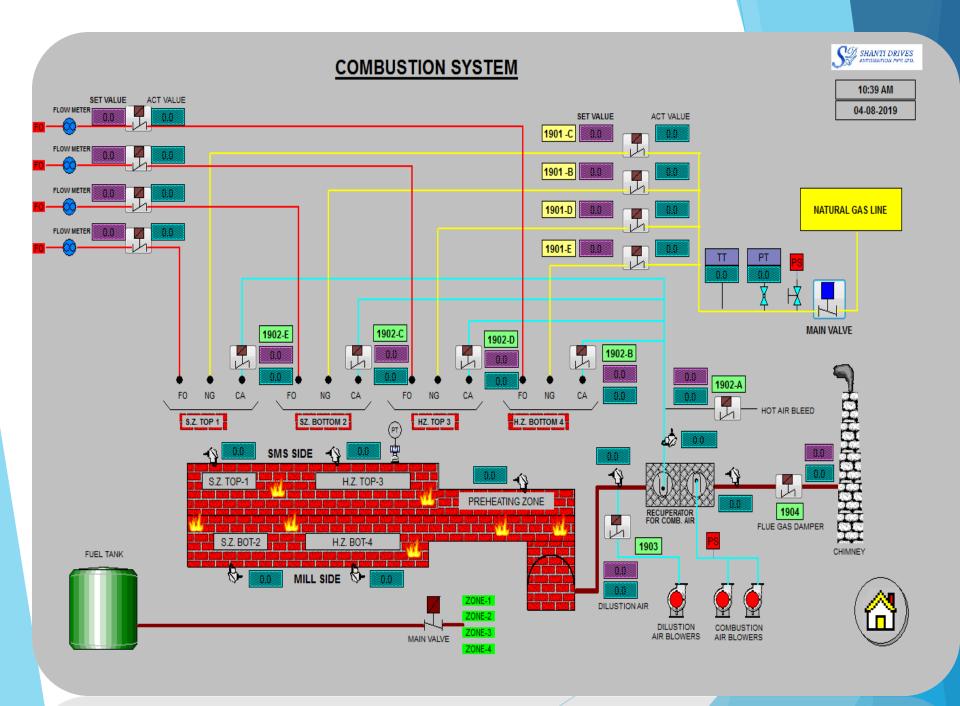
### TMT AREA LINE 02

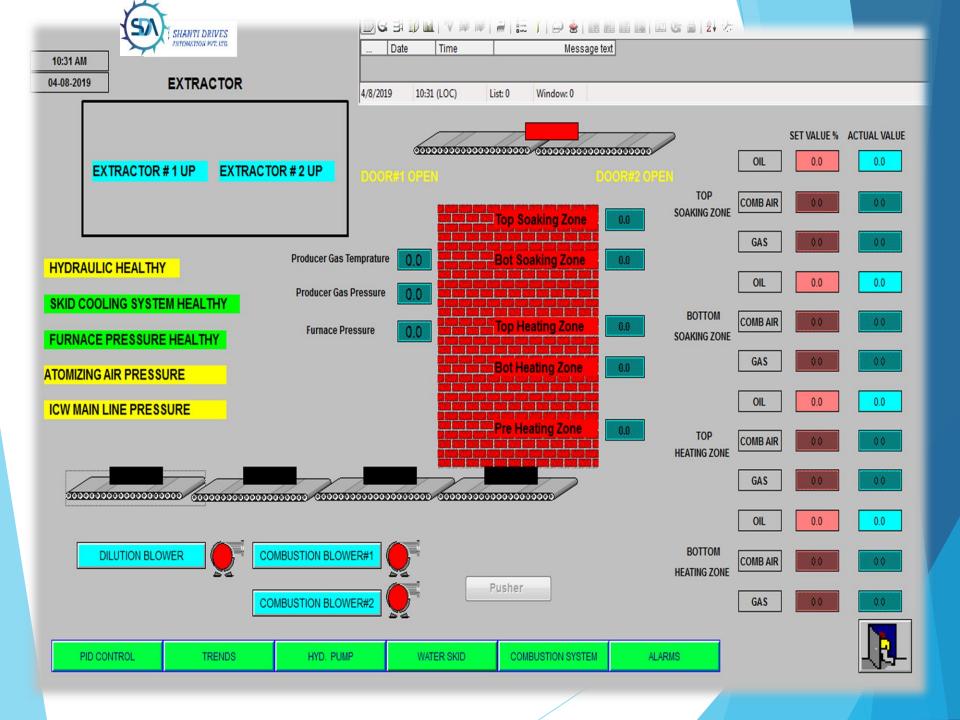
		LUES —	GEAR	ROLL
	RPM	CURRENT	RATIO	DIAMETER
PR 1	1500	114	1.000	300
PR 2	1500	114	1.000	300
FS	700	500	2.000	1010
LTB	1500	114	1.000	300
RTB	1500	114	1.000	300

### DISTANCES FROM HMD (mm) LINE 02

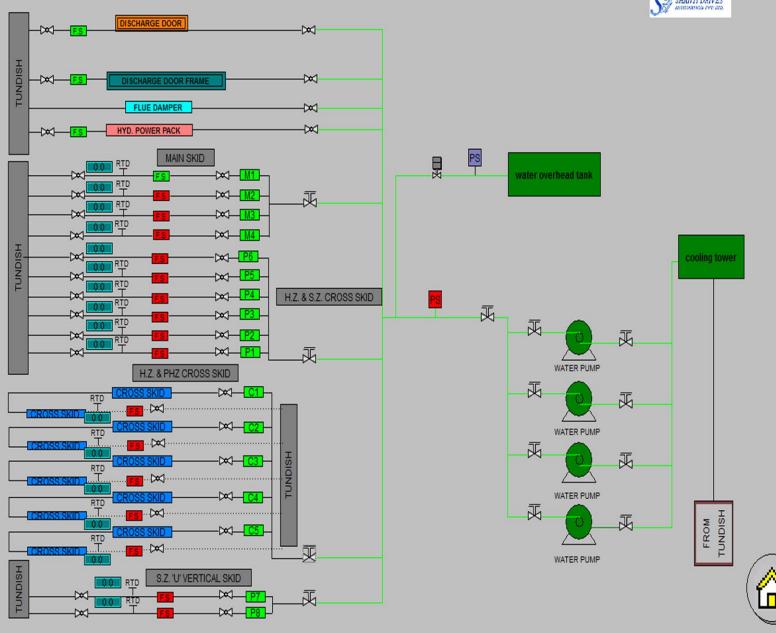
PR 1	PR 2	FS	LTB	RTB
1930	14280	16250	24450	26650









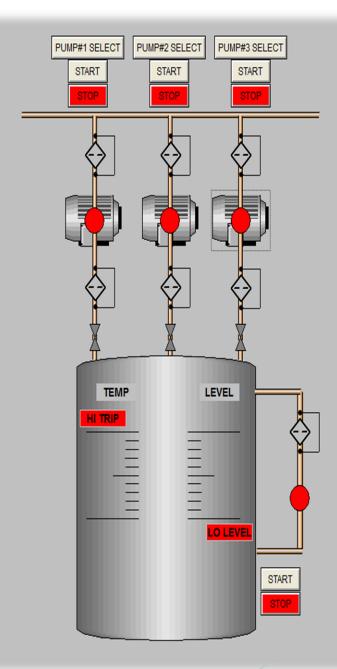




### HYDRAULIC OPERATION FOR REHEATING FURNACE

HYDRAULIC PUMP-1	STATUS
HYD PUMP-1 STOP	•
HYD PUMP-1 TRIP	•
OIL LEVEL EMPTY	•
OIL TEMP. HIGH TRIP	•
PUMP-1 SUCTION LINE	•
RECIRCULATION PUMP ON	•
E-STOP	•

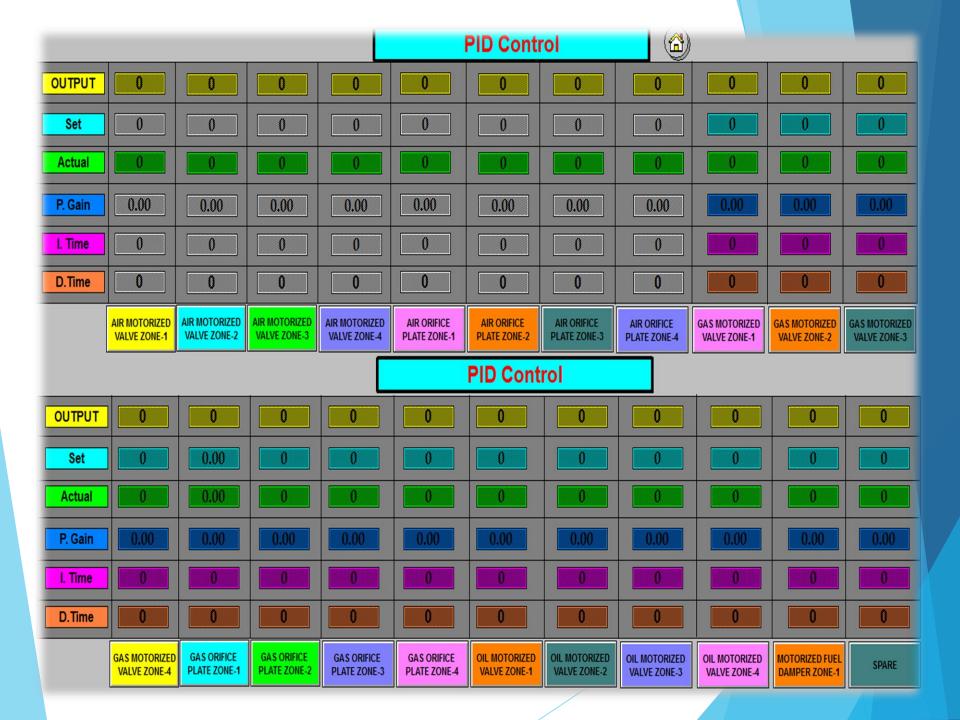
HYDRAULIC PUMP-2	STATUS
HYD PUMP-2 STOP	•
HYD PUMP-2 TRIP	•
OIL LEVEL EMPTY	•
OIL TEMP. HIGH TRIP	•
PUMP-2 SUCTION LINE	•
RECIRCULATION PUMP ON	•
E-STOP	•

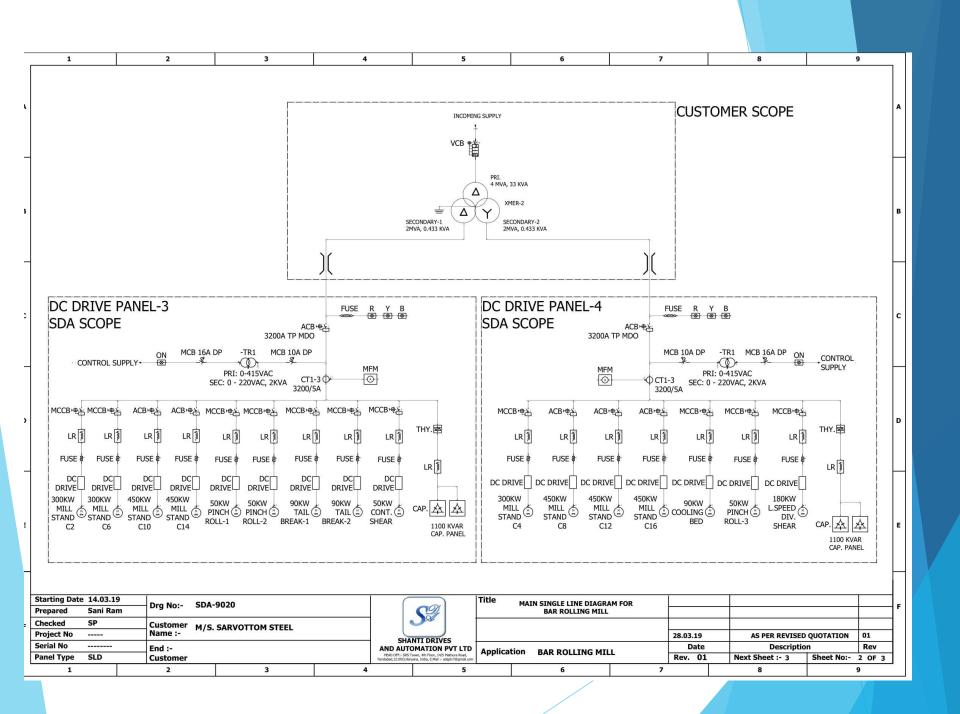


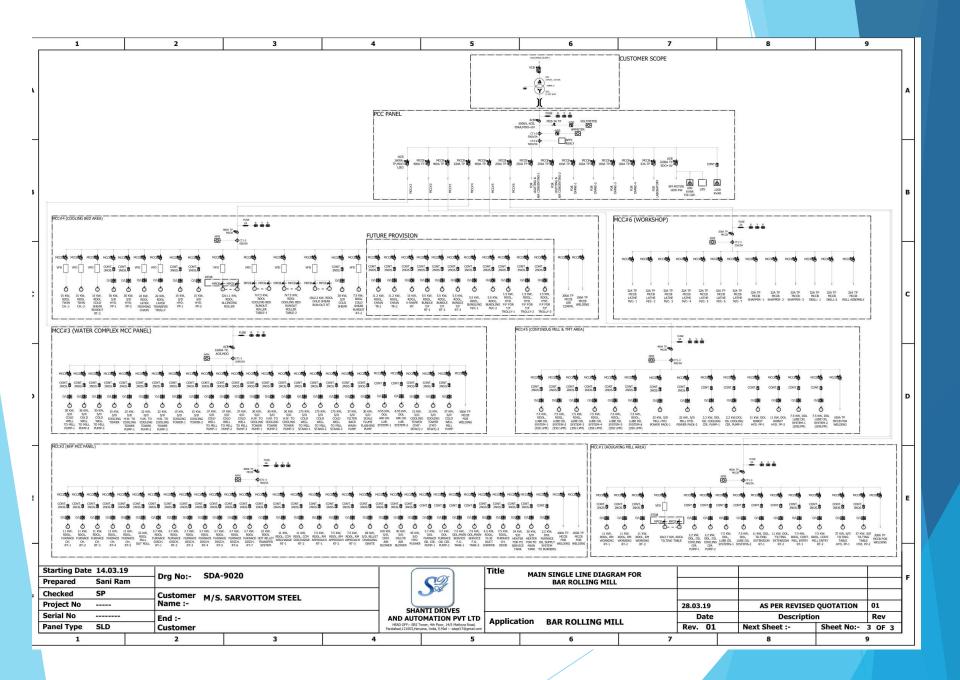
HYDRAULIC PUMP-3	STATUS
HYD PUMP-3 STOP	•
HYD PUMP-3 TRIP	•
OIL LEVEL EMPTY	•
OIL TEMP. HIGH TRIP	•
PUMP-3 SUCTION LINE	•
RECIRCULATION PUMP ON	•
E-STOP	•

RECIRCULATION PUMP	STATUS
RECIR. PUMP STOP	•
RECIR. PUMP TRIP	•
OIL LEVEL EMPTY	•
E-STOP	•

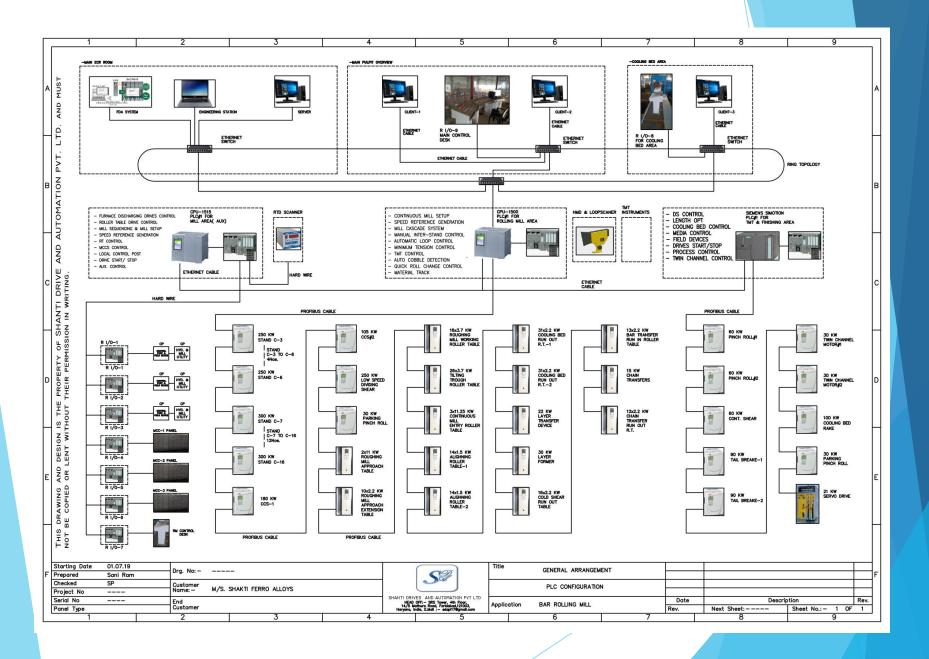






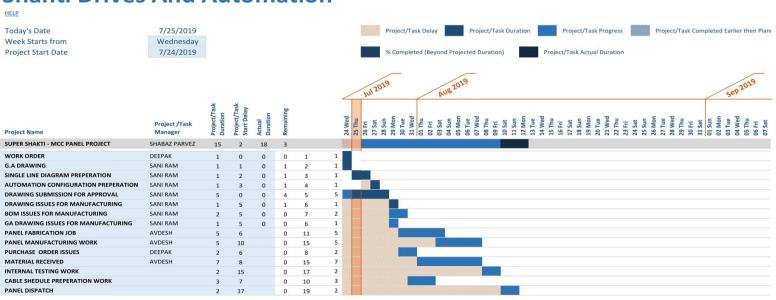


### **AUTOMATION CONFIGURATION**



## PROJECT EXECUTION CHART

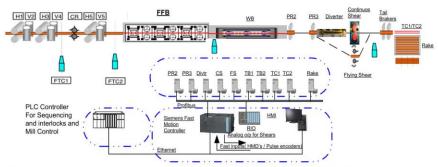
### **Shanti Drives And Automation**



Project Planner by Spreadsheet123.com © 2015 Spreadsheet123 LTD.

# AIC TECHNOLOGICAL PACKAGE

#### TECHNOLOGICAL PACKAGE FOR HI SPEED BAR MILLS ~40m/s



#### CONTROL FUNCTIONS

- Start / Stop Shear Axis control. It is the heart of the control of LO speed shear system. It controls the position of the shear knives to assure precision and repeatability of the cut length. To perform this function it receives as inputs the encoder of the stand, the encoder of the shear, the hot metal detector and the proximity switch and generates as output the speed or torque request for the shear drive.
- Rotating shears are the leading edge technology when high speed and accuracy are required. These targets are achieved by an optimized combination of motion control strategies aimed to get the best performance with the minimum effort from the machine, Fast dynamic motion applied to rotating blades and diverter are necessary to deliver highly versatile and accurate rotating shears, capable of doing head and tail crop, scrapping and cut to measure at a speed of up to 100m/s.
- Control is provided for the opening and closing of Pinch rolls, normally the Pinch roll is closed and controlled with a set torque limit in order to follow the bar speed, the tracking function opens up the torque limit of the pinch roll as the bar leaves the last finishing stand to enable the Pinch rolls to run at a speed that was memorized while the bar was being rolled in the finishing stand
- The primary function of the braking PR is to ensure that the bars fall on the cooling bed with all their tails (or optionally heads) aligned.
- The bar kick-off device and the rake act in synchronism with the braking pinch rolls. When the tracking system determines that the bar delivered by the rake has come to a stop, the kick-off device acts and kicks the bar out of the cooling bed delivery channels. The rake times itself and starts early enough so that the moving grates pick up the bar as soon as it drops on the fixed rake.

#### SCOPE OF WORK

- The hardware for Shear Control is based on Powerful Siemens Controllers, Simotion C240
- HMI is based on Operator Panel from Siemens
- Communication to Master Speed & Sequence controller is either through Profibus / Ethernet interface.
- Analog Input / Analog out put interfaces are provided for interfacing other high speed signals required for implementing Shear Control
- Drives can be existing or new depending on the project condtions

#### PERFORMANCE FIGURES IN SIMILAR PLANTS

- The tolerance shall vary based on speed of the material in the previous stand. If the speed is constant the tolerance doesn't vary based on cut length
- shear cut accuracy: <= +/- 100 mm (cut to cut)</li>
   First cut accuracy depends on the possibility to change the position of
- the blades of the shear wrt approaching material, or if the layout permits enough time to adjust the position of the blades.

  Our optimization system will recalculate the bar length for cooling bed
- Our optimization system will recalculate the bar length for cooling bed entry cutting to ensure that all bars going to the cooling bed are within acceptable range. (No short lengths or no over lengths) for bar discharge on to cooling bed.
- In some cases it was possible to improve the speed from 24mlsec to 30mlsec or to improve the tolerances up to ±1cm just replacing the automation part without impact on plant layout or mechanical equipment.

#### PRECONDITIONS

- The mill is mechanically and hydraulically capable of achieving the target size and maintaining the size within tolerance
- Existing drives shall satisfy the static (±0.02% of the maximum speed) / dynamic (0.2%s) speed performance criteria,
   Existing Field devices working well
- Stable rolling conditions (temperature, elongation, Speed stability)

#### **ADVANTAGES**

- Control system applied on new / existing machines
  - Cut repeatability: The system is designed to achieve the highest possible cut repeatability to allow high optimization of cutting strategies
- Head / Tail Cuts: It optimize the length of these cuts because of its very fast reaction to external signals (HMD's) and high repeatability
- Cut to length: The system accurately tracks the length of the material being processed by means of Encoder signals, to allow cuts to any desired length with high accuracy and repeatability
- Ghost Billet: The system is provided to simulate a rolling process and checks the shear cycle before or during a rolling campaign
- Solution based on standard market available products from Siemens ,
  Drives can be any of make Siemens / ABB / Danfoss/ Parker
- All presented control technologies are flexible and support different set ups, that are required for different products and different mechanical arrangements, such as shears with a combination of flying and crank arms and optional flywheel.
- Optimized parameters for different productions are easily selected by an integrated recipe system, and combined with automatically computed motion paths bring several advantages:
  - Reduce mechanical stress and wear
  - Reduce operating noise
  - Reduce electrical stress on both drive and motor
  - Reduce energy requirements
  - Allow a cost effective selection of motors and drives

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# PANEL GALLERY (SIDDHI LAXMI)





# PANEL GALLERY (TIRUPATI)



# MILL ENTRY AREA



# TMT & COOLING BED AREA



# MAIN ECR ROOM



## **MAIN PULPIT**



# MAIN PULPIT INSIDE



# PLC PANEL





















- ▶ JORAWAR ISPAT , RAIPUR (14+1)
- ► SEEMA STEELS , BANGLADESH(14+1)
- ► NAV DURGA ,HYDERABAD(12+1)
- ▶ PENINSULA STEELS MILLS ,CHITTAGONG, BANGLADESH
- ► KADAMTALI STEELS MILLS, DHAKA, BANGLADESH
- BANDAR ISPAT , DHAKA, BANGLADESH
- RAHIM STEEL, DHAKA, BANGLADESH
- ► ECO PLUS, SATNA, MP
- BRGD INGOT PVT.LTD. BALMUKUND
- SIETZ TECH PVT. LTD







# THANK YOU



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